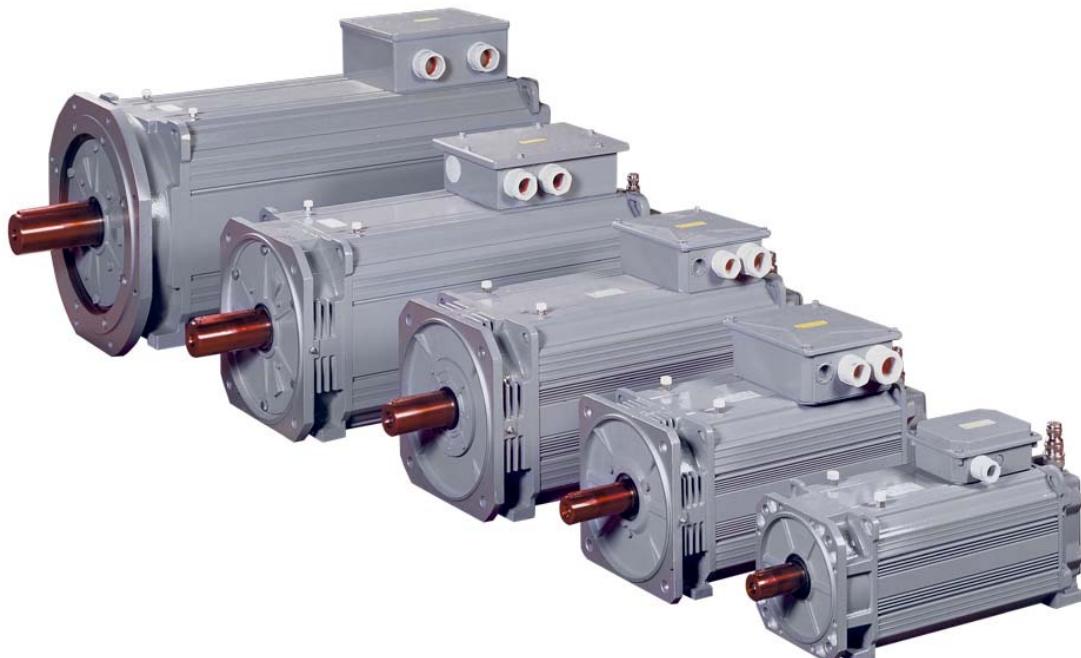


**Servomotori A.C. 3-f. raffreddati a LIQUIDO
LIQUID cooled A.C. 3-phase servomotors
Servomotoren, FLÜSSIGKEITSGEKÜHLT**

LQ Sincrovert®



**Size 100 ÷ 225
KW 3.2 ÷ 318**

DATI GENERALI		GENERAL DATA		ALLGEMEINE DATEN					
Forma costruttiva	Mounting	Bauformen		Size 100-180 IM 2001 (B35) - Size 225 IM 1001 (B3) or IM 3001 (B5) ²⁾					
Protezione motore	Motor Protection	Schutzart		IP 54					
Equilibratura	Balancing	Schwinggüte		grado R - R degree - grad R					
Isolamento	Insulation	Isolation		classe F - F class - F Klasse					
Protezione termica	Thermal Protection	Thermikschutz		PTO (Klixon) - PTC ²⁾ - PT100 ²⁾					
Rumore L _w	Noise L _w	Geräuschpegel L _w		L _w < 75 dB (A)					
Raffreddamento	Cooling System	Kühlung		IC 9W7 - A liquido - liquid cooled					
Installazione	Ambient	Umgebungstemperatur		+ 3 / + 60°C					
Altitudine	Altitude	Meereshöhe		0 - 3000m a.s.l.					

RAFFREDDAMENTO		COOLING							
Grandezza motore	Motor size	MotorBaugröße	Size	100	132	160	180	225	
Portata liquido	Liquid delivery	Durchflußmenge	l/min	8	10	12	15	18	
Capacità di raffreddamento	Cooling capacity	Kühlleistung	kW			= Pn - (0,95 * Pn * η %)			
Pressione massima	Max perm. pressure	Max. Druck	Bar	3	3	3	3	3	
Caduta di pressione max.	Max pressure drop	Maximaler Druckfall	Bar	0.5	0.5	0.8	0.9	0.9	
Temperatura liquido *	Coolant temperature *	Kühlmittel-Temperatur *		18°C (min. 16°C) in funzionamento nominale - at rated operation					
Qualità liquido	Type of coolant	Kühlmittel		Acqua + liquidi anticorrosivi/antigelo Water + antcorrosion/no-frost additives (max 20%)					
Circuito di raffreddamento	Cooling circuit	Kühlkreislauf		Chiuso con scambiatore di calore esterno - Closed with external heat-exchanger					
Coef. di declassamento	Derating coefficient	Herabsetzungskoeffizient		For input liquid temperature higher than 18°C. see pag. B11 for derating diagram					

* in ingresso – input temperature - Eintrittstemperatur , Vedere pag. B11, see page B11, Sie Seite B11

TRASDUTTORE ²⁾		TRANSDUCER ²⁾		MEßWANDLER ²⁾					
Encoder	Encoder	Drehgeber		Preferential type	1024 ppr 5V TTL 2 channels + marker	– supply voltage	5Vdc		
Tipo diversi a richiesta	Different type on requ.	Andere Typen auf Anfrage			HTL - Push-pull - 1V p/p	- Sinus - Absolute	- Hiperface	- SSI -	

Vedere pag. B11, see page B11, Sie Seite B11

FRENO ²⁾		BRAKE ²⁾		BREMSE ²⁾					
Motore	Freno	Coppia statica	Alimentazione - Power supply	Inerzia (J)	Velocità max.	Tempi - Times	Lavoro ammissibile		
Motor	Brake	Static torque	Rectifier	Coil	inertia (J)	Max. speed	sw. ON	sw. OFF	Max admissible work
Size	Type	Nm (max)	Input Vac - Hz	Vdc	W	Kgm ²	rpm	ms	J
100	R 50	50	230 - 50/60	96	25	0,0006	6000	70	110
100	K 6	60	230 - 50/60	96	50	0,0007	5000	80	150
132	Rr 150	130	230 - 50/60	96	30	0,0023	6000	90	180
132	K 8 (K8 D)	150 (300)	230 - 50/60	96	60	0,0028 (0,006)	4000 (3500)	150	300
160	Rr 180	160	230 - 50/60	96	55	0,0028	5000	140	260
160, 180	K9 (K9 D)	200 (400)	230 - 50/60	96	65	0,004 (0,0085)	3000 (2500)	190	400
180, 225	Rr 360 (Rr360 D)	900 (1800)	230 - 50/60	96	190	0,018 (0,036)	2000 (1500)	330	600
									J _{tot} * Δn ²
									182.5
									See pag. B12

Serie K: Coppia frenante regolabile, Adjustable braking torque.

() Versione a doppio disco, non è consentito il funzionamento in verticale – Double disk version, the vertical mounting is not permitted.

CUSCINETTI		BEARINGS		WÄLZLAGER						RADIAL LOAD DIAGRAM		
Size	D.E. side Brg. code	N.D.E. side Brg. code	Max. speed ³⁾ Rpm	Max. rad. load N @ 1500rpm	Distance X mm					Max axial load N		
100	6308ZZ (TBH) ²⁾ NJ 308 EC ²⁾	6207ZZ (TBH) ²⁾	7500 (12000) ²⁾ 6700 ²⁾	1700 / 1500 3100 / 2700	40 / 80					1100		
132	6309ZZ C3 (TBH) ²⁾ NJ 309 EC ²⁾	6209ZZ C3 (TBH) ²⁾ 6209ZZ (INS) ²⁾	6700 (8000) ²⁾ 6300 ²⁾	2600 / 2200 4900 / 4300	55 / 110					1500		
160	6312ZZ C3 (TBH) ²⁾ NJ 312 EC ²⁾	6311ZZ C3 (TBH) ²⁾ 6311 (INS) ²⁾	5300 (7500) ²⁾ 4800 ²⁾	4300 / 3800 7000 / 6000	55 / 110					1800		
180	6314 C3 (TBH) ²⁾ NJ 314	6312 C3 (TBH) ²⁾ 6312 (INS) ²⁾	4300 (6300) ²⁾ 3800 ²⁾	6600 / 5600 9800 / 7000	70 / 140					2000		
225	6318 C3 (TBH) ²⁾ NJ 318 EC ²⁾	6315 C3 (TBH) ²⁾ 6315 (INS) ²⁾	3400 (5000) ²⁾ 2800 ²⁾	7000 / 6000 12000/11000	70 / 140					4000		

D.E. (Lato comando, drive end, Abtriebsseite) - N.D.E. (Lato opposto comando, non-drive end, Rückseite)

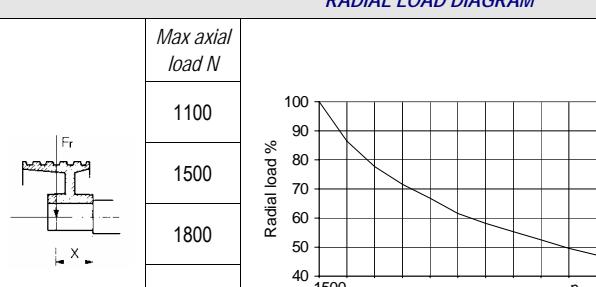
2) Opzione disponibile a richiesta – Option available on request – Verfügbares Sonderzubehör

3) La velocità massima continuativa è limitata al 70% del valore indicato - The max continuous operation speed is limited to the 70% of the indicated value.

NJ-NU (Cuscinetto a ruoli, Roller bearing, Rollenlager) ²⁾

TBH (Cuscinetto alta velocità, High speed bearing, Hochtourige Wälzlagar) ²⁾

INS (Cuscinetto isolato elettricamente - Electrically insulated bearing – Elektrisch isoliertes Rollenlager) ²⁾



DATI ELETTRICI E PRESTAZIONI								ELECTRICAL DATA AND PERFORMANCES				ELEKTRISCHE DATEN UND LEISTUNGEN																								
	n_n 580 rpm f _n 19.3 Hz		n_n 1000 rpm f _n 33.3 Hz		n_n 1500 rpm¹⁾ f _n 50 Hz ¹⁾		n_n 1800 rpm f _n 60 Hz		n_n 2200 rpm f _n 73.3 Hz		n_n 2600 rpm f _n 86.6 Hz																									
Motor Type	P _n Kw	A (400V) M _n Nm	A (400V) η %	P _n Kw	A (400V) M _n Nm	A (400V) η %	P _n Kw	A (400V) M _n Nm	A (400V) η %	P _n Kw	A (400V) M _n Nm	A (400V) η %	n _{max} ⁶⁾ Rpm	M _{max} Nm	J Kgm ²	W Kg																				
LQ 100M	3,2 52,3	7,6 75,3	5,2 49,9	11,5 82,1	7,5 47,5	15,9 84,6	9,0 47,5	19,1 84,9	10,1 43,7	21,3 85,2	11,0 40,4	23,2 85,7	7500 ¹⁾ 12000 ²⁾ 6700 ³⁾	70	0.0113	60																				
LQ 100L	4,5 73,7	10,9 76,2	7,4 70,4	16,4 83,0	10,5 67,0	22,8 85,6	12,6 67,0	27,3 85,9	14,2 61,6	30,5 86,2	15,5 57,0	33,1 86,7		95	0.0144	75																				
LQ 100X	6,4 105	15,3 77,4	10,5 100	23,1 84,4	15,0 95,5	31,9 87,0	18,0 95,5	38,2 87,3	20,2 87,9	42,8 87,6	22,1 81,2	46,5 88,1		140	0.0202	90																				
LQ 132S	8,6 141	18,0 81,7	14,0 134	27,2 89,0	20,0 128	37,7 91,8	24,0 128	45,1 92,1	27,0 118	50,5 92,4	29,6 109	54,8 93,0	6700 ¹⁾ 8000 ²⁾ 6300 ³⁾	260	0.075	95																				
LQ 132L	12,8 210	26,9 82,7	21,0 201	40,6 90,1	30,0 191	56,2 92,9	36,0 191	67,3 93,2	40,5 176	75,3 93,6	44,2 162	81,8 94,1		380	0.109	120																				
LQ 132P	15,8 260	33,2 83,6	26,0 248	50,2 91,1	37,0 236	69,6 93,9	44,5 236	83,2 94,2	50,0 217	93,2 94,6	54,6 201	101 95,1		470	0.123	130																				
LQ 132X	18,3 301	37,4 83,3	30,0 288	56,4 90,8	43,0 274	78,2 93,6	51,6 274	93,5 93,9	58,0 252	105 94,3	63,4 233	114 94,8		540	0.151	150																				
LQ 160M	21,3 351	44,1 84,2	35,0 335	66,5 91,8	50,0 319	92,2 94,6	60,0 319	110 94,9	67,6 293	124 95,3	73,8 271	134 95,8	5300 ¹⁾ 7500 ²⁾ 4800 ³⁾	640	0.290	215																				
LQ 160L	25,5 420	50,8 84,4	42,0 401	76,7 92,0	60,0 382	106 94,8	72,0 382	127 95,1	81,0 351	143 95,5	88,4 325	155 96,0		760	0.341	240																				
LQ 160P	30,0 491	60,0 84,4	49,0 468	90,7 92,0	70,0 446	126 94,8	84,0 446	150 95,1	94,5 410	168 95,5	103 379	183 96,0		860	0.387	265																				
LQ 160X	36,0 595	72,8 84,4	59,5 568	110 92,0	85,0 541	152 94,8	102 541	182 95,1	115 498	204 95,5	125 460	222 96,0		1100	0.510	325																				
LQ 180M	46,8 770	94,2 84,4	77,0 735	142 92,0	110 700	197 94,8	132 700	236 95,1	148 644	264 95,5	162 595	287 96,0	4300 ¹⁾ 6300 ²⁾ 3800 ³⁾	1400	0.690	420																				
LQ 180L	56,1 924	113 84,4	92,4 882	171 92,0	132 840	237 94,8	158 840	283 95,1	178 773	317 95,5	194 714	344 96,0		1700	0.810	480																				
LQ 180X	61,7 1015	124 84,4	101 969	188 92,0	145 923	260 94,8	174 923	311 95,1	196 849	348 95,5	214 785	378 96,0		1850	0.990	540																				
LQ 225L	63,8 1051	129 84,4	105 1003	194 92,0	150 955	269 94,8	180 955	322 95,1	202 879	360 95,5			3400 ¹⁾ 5000 ²⁾ 2800 ³⁾	1900	1.65	760																				
LQ 225P	74,8 1232	151 84,4	123 1176	228 92,0	176 1120	315 94,8	211 1120	377 95,1	237 1030	423 95,5				2200	1.91	860																				
LQ 225X	91,9 1513	185 84,4	151 1444	280 92,0	216 1375	387 94,8	259 1375	463 95,1	291 1265	519 95,5				2700	2.27	1000																				
POWER DIAGRAM					TORQUE DIAGRAM					LQ																										
										<table border="1"> <thead> <tr> <th>n_n</th> <th>n₁⁴⁾</th> <th>n₁⁵⁾</th> </tr> </thead> <tbody> <tr><td>580</td><td>1740</td><td>1400</td></tr> <tr><td>1000</td><td>3000</td><td>2400</td></tr> <tr><td>1500</td><td>4500</td><td>3600</td></tr> <tr><td>1800</td><td>5400</td><td>4300</td></tr> <tr><td>2200</td><td>6600</td><td>5200</td></tr> <tr><td>2600</td><td>7800</td><td>6200</td></tr> </tbody> </table>					n _n	n ₁ ⁴⁾	n ₁ ⁵⁾	580	1740	1400	1000	3000	2400	1500	4500	3600	1800	5400	4300	2200	6600	5200	2600	7800	6200	
n _n	n ₁ ⁴⁾	n ₁ ⁵⁾																																		
580	1740	1400																																		
1000	3000	2400																																		
1500	4500	3600																																		
1800	5400	4300																																		
2200	6600	5200																																		
2600	7800	6200																																		

¹⁾ 400V 50Hz 1500rpm velocità ed avvolgimento standard – standard speed and winding - Cuscinetti, Bearings, Wälzlagler: (sfere, ball, sphäre) ¹⁾ – (alta velocità, high speed, Hochtourige Wälzlagler) ²⁾ - (rulli, roller, Rollenlager) ³⁾

⁴⁾ Non superiore al limite max. di velocità n_{max} – Not higher than the limit speed n_{max} - Nicht höher als max. Drehzahlgrenze n_{max}

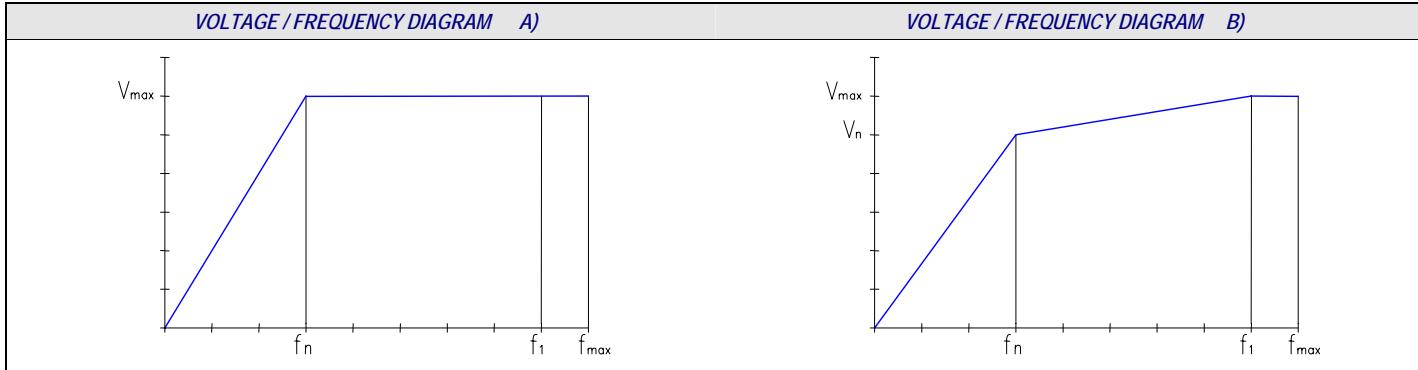
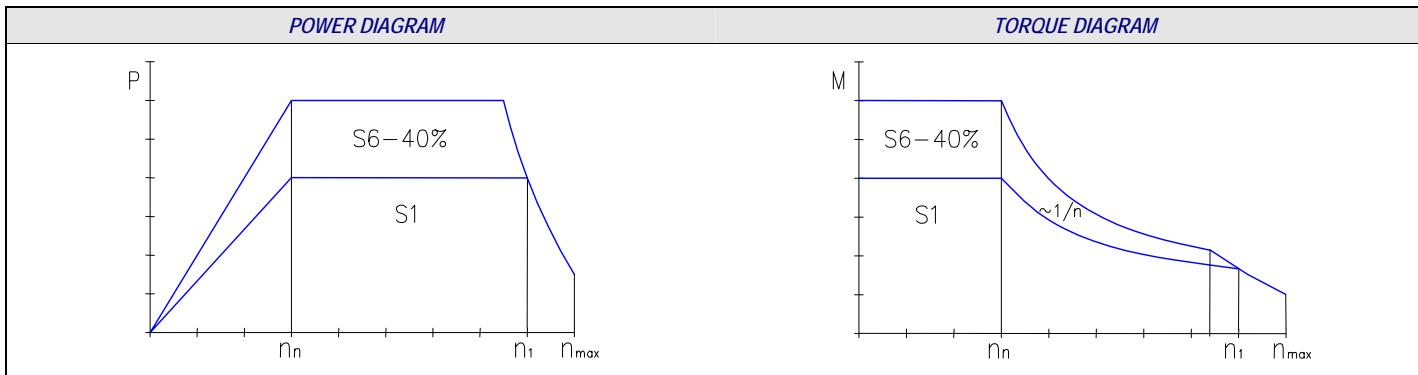
⁵⁾ Con incremento di min. 70V tra n_n e n₁ – Increasing the voltage by minimum 70V between n_n and n₁ – Bei Erhöhung um mindestens 70V zwischen n_n und n₁

⁶⁾ Senza incremento di tensione tra n_n e n₁ – Without voltage increase from n_n and n₁ – Ohne Spannungserhöhung zwischen n_n und n₁

⁷⁾ La velocità massima continua è limitata al 70% del valore indicato - The max continuous operation speed is limited to the 70% of the indicated value.

LEGENDA DELLE TABELLE				KEY WORDS				KURZZEICHEN						
DATI ELETTRICI E PRESTAZIONI							ELECTRICAL DATA AND PERFORMANCES			ELEKTRISCHE DATEN UND LEISTUNGEN				
	n_n 580 rpm f _n 19.3 Hz		n_n 1000 rpm f _n 33.3 Hz		n_n 1500 rpm f _n 50 Hz		n_n 1800 rpm f _n 60 Hz		n_n 2200 rpm f _n 73.3 Hz		n_n 2600 rpm f _n 86.6 Hz			
Motor Type	P _n Kw M _n Nm	A (400V) η %	P _n Kw M _n Nm	A (400V) η %	P _n Kw M _n Nm	A (400V) η %	P _n Kw M _n Nm	A (400V) η %	P _n Kw M _n Nm	A (400V) η %	n _{max} Rpm	M _{max} Nm	J Kgm ²	W Kg

n_n	Velocità di rotazione nominale	Nominal speed	Nenn Drehzahl
n₁	Velocità di rotazione massima a pot. costante (P _n)	Maximum speed at constant power (P _n)	Max. Drehzahl bei konstanter Leistung (P _n)
n_{max}	Velocità max. di rotazione a potenza ridotta (non per servizio continuativo)	Maximum speed at reduced power (not in continuous duty)	Max. Drehzahl bei reduzierter Leistung (nicht bei Dauerbetrieb)
P_n	Potenza meccanica nominale resa all'albero per servizio S1	Nominal mechanical power at the shaft for service factor S1	Mechanische Nennleistung an der Welle bei Dauerbetrieb S1
M_n	Coppia nominale resa all'albero	Nominal torque at the shaft	Nenn Drehmoment an Welle
V_n	Tensione nominale del motore	Motor nominal voltage	Nenn Spannung
V_{max}	Tensione massima erogata dall'inverter	Max inverter output voltage	Max Spannung
f_n	Frequenza nominale	Nominal power supply frequency	Nenn-Versorgungsfrequenz
f₁	Frequenza alla velocità n ₁	Frequency at n ₁ speed	Versorgungsfrequenz bei Drehzahl n ₁
f_{max}	Frequenza massima	Max frequency	Max.Versorgungsfrequenz
A	Corrente nominale	Nominal current	Nennstrom
η	Rendimento a pieno carico	Full load motor efficiency	Motorleistung bei Vollast
M_{max}	Coppia max erogabile dal motore	Maximum output motor torque	Max. Abgabemoment des Motors
J	Momento d'inerzia rotorico	Rotor inertia	Rotorisches Drehzahlmoment
W_g	Peso del motore	Motor weight	Motorgewicht
S1	Area di funzionamento in servizio continuativo S1	Operation area for continuous service factor S1	Einschaltbereich bei Dauerbetrieb S1
S6	Area di funzionamento in sovraccarico con servizio periodico S6-40%	Operation area at overload for intermittent operation S6-40%	Einschaltbereich bei Überlast im Aussetzbetrieb S6-40%

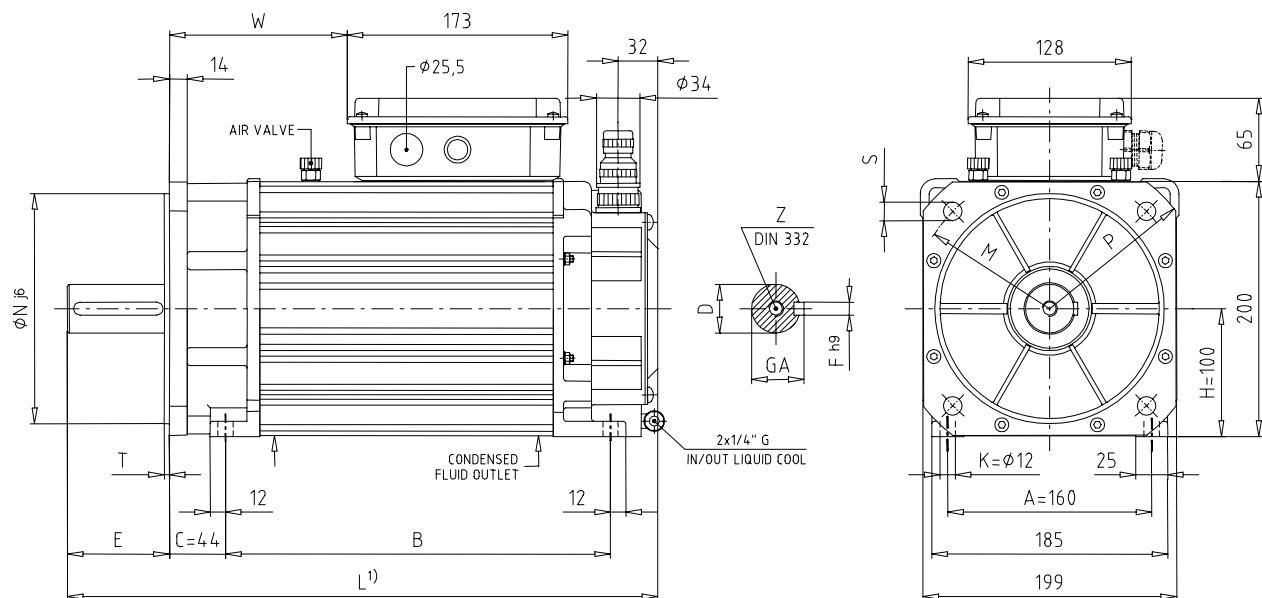


- Note La velocità n₁ con funzionamento a potenza costante (P_n) è ottenibile solo con un incremento della tensione erogata dall'inverter di minimo 70V tra n_n e n₁ (f_n e f₁).
The n₁ speed, when operating at constant power (P_n), is only available by increasing the voltage from the inverter by at least 70V between n_n and n₁ (f_n and f₁).
 Die Drehzahl n₁ bei Betrieb mit konstanter Leistung (P_n) ist nur bei Erhöhung der Spannung aus dem Stromumrichter um mindestens 70V zwischen n_n und n₁ (f_n und f₁) erzielbar.
 A) Funzionamento a potenza costante limitato (70% di n₁) - Limited constant power operation range (70% of n₁) - Begrenzter Konstant-Leistungsbereich (70% von n₁)
 B) Funzionamento a potenza costante esteso (P_n @ n₁) - Extended constant power operation range (P_n @ n₁) - Erweiterter Konstant-Leistungsbereich (P_n @ n₁)

LQ 100

DIMENSIONI DI INGOMBRO - OVERALL DIMENSIONS - ABMESSUNGEN

Dimensions [mm]

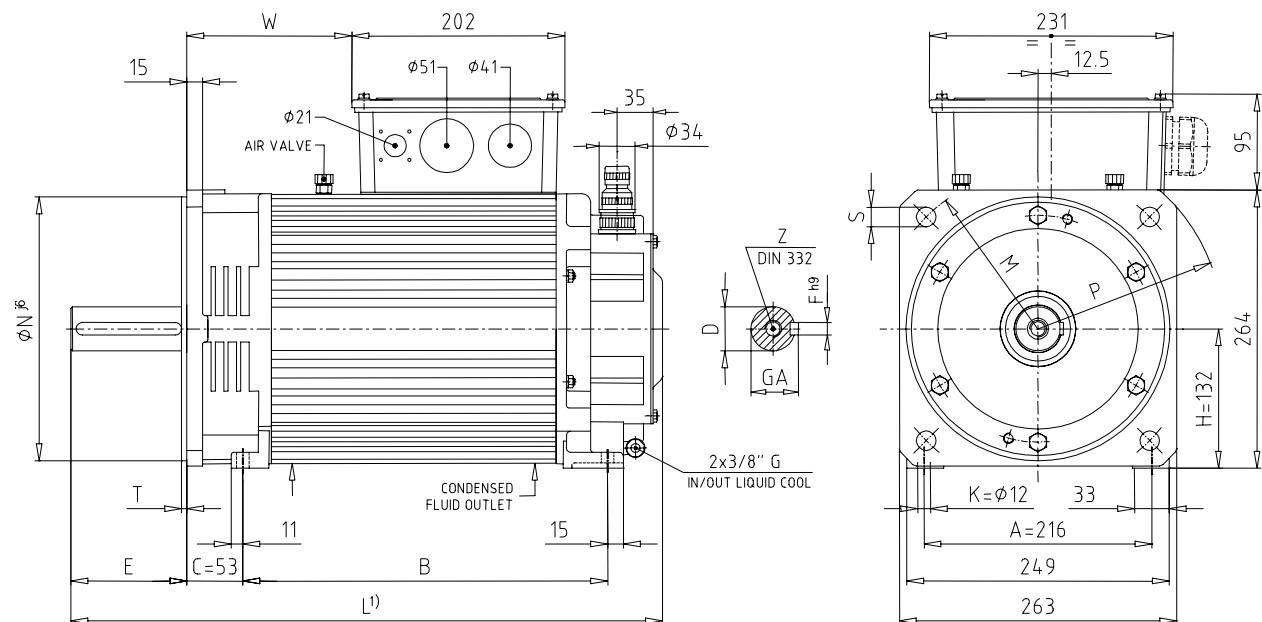


Size	B	D	E	F	GA	L	L1	M	N	P	S	T	W	Z
100 M	302					460	90 a)						134	
100 L	362	38 ^{k6}	80	10	41	520	140 b)	215	180	250	14.5	4	194	M12
100 X	422					580							254	

LQ 132

DIMENSIONI DI INGOMBRO - OVERALL DIMENSIONS - ABMESSUNGEN

Dimensions [mm]



Size	B	D	E	F	GA	L	L1 ²	M	N	P	S	T	W	Z
132 S	346					565	120 c)						155	
132 L	421	42 ^{k6}	110	12	45	640	145 d)	300	250	350	18.5	5	230	
132 P	451					670	170 e)						260	M16
132 X	511					730	195 f)						320	

Note: ¹⁾ Per motori LQ con freno aggiungere la quota L1 – For LQ motors with brake add L1 quote - Bei LQ Bremsmotoren Wert L1 hinzufügen.

a) freno tipo K7 - brake type K7 - bremse typ K7 - b) freno tipo K7 + encoder - brake type K7 + encoder - bremse typ K7 + encoder

c) freno tipo K8 - brake type K8 - bremse typ K8 - d) freno tipo K8D - brake type K8D - bremse typ K8D

e) freno tipo K8 + encoder - brake type K8 + encoder - bremse typ K8 + encoder - f) freno tipo K8D + encoder - brake type K8D + encoder - bremse typ K8D + enc.

²⁾ Opzione disponibile a richiesta – Option available on request – Verfügbares Sonderzubehör

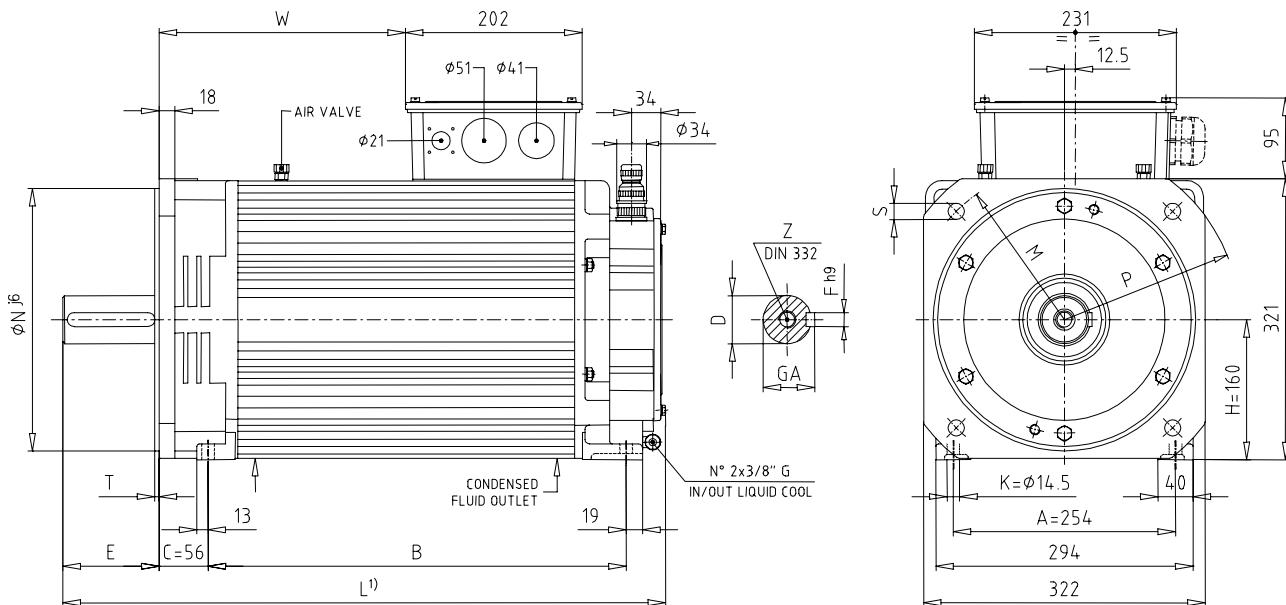
Pressacavi non forniti – Cable glands not included in the supply - Kabeltüllen gehören nicht zum Lieferumfang

Vedere condizioni di montaggio a pag. 11 – See mounting positions on page 11 - Beachten Sie bitte die Bedingungen der Montage auf Seite 11

LQ 160

DIMENSIONI DI INGOMBRO - OVERALL DIMENSIONS - ABMESSUNGEN

Dimensions [mm]

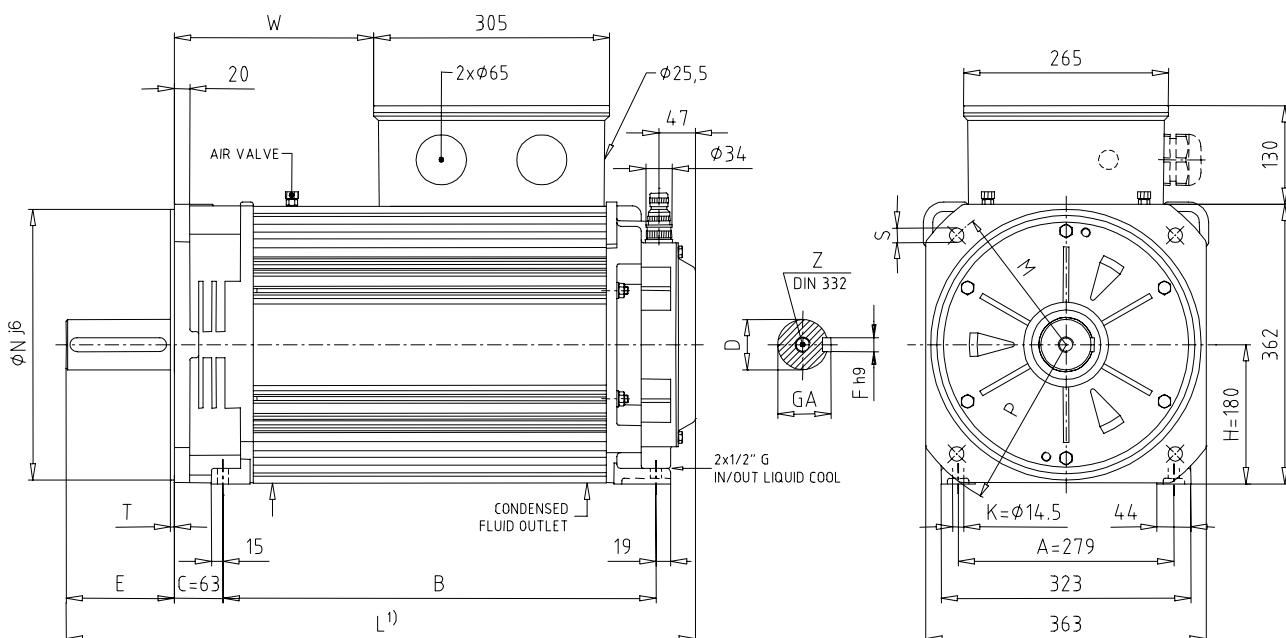


Size	B	D	E	F	GA	L	L1 ²⁾	M	N	P	S	T	W	Z
160 M	513					725	125 a)						316	
160 L	563	55 m ⁶	110	16	59	775	150 b)						366	
160 P	608					820	175 c)	350	300	400	18.5	5	411	M20
160 X	735					947	200 d)						538	

LQ 180

DIMENSIONI DI INGOMBRO - OVERALL DIMENSIONS - ABMESSUNGEN

Dimensions [mm]



Size	B	D	E	F	GA	L	L1 ²⁾	M	N	P	S	T	W	Z
180 M	680					940							378	
180 L	750	65 m ⁶	140	18	69	1010	120 e)	400	350	450	18.5	5	448	M20
180 X	870					1130	170 f)						568	

Note: ¹⁾ Per motori LQ con freno aggiungere la quota L1 – For LQ motors with brake add L1 quote - Bei LQ Bremsmotoren Wert L1 hinzufügen.

a) freno tipo K9 - brake type K9 - bremse typ K9 - b) freno tipo K9D - brake type K9D - bremse typ K9D

c) freno tipo K9 + enc. - brake type K9 + enc. - bremse typ K9 + enc. - d) freno tipo K9D + enc. - brake type K9D + enc. - bremse typ K9D + enc.

e) Freno tipo Rr 360 - brake type Rr 360 - bremse typ Rr 360 - f) Freno tipo Rr 360 + enc. - brake type Rr 360 + Enc. - bremse typ Rr 360 + Enc.

²⁾ Opzione disponibile a richiesta – Option available on request – Verfügbares Sonderzubehör

Pressacavi non forniti – Cable glands not included in the supply - Kabeltüllen gehören nicht zum Lieferumfang

Vedere condizioni di montaggio a pag. 11 - See mounting positions on page 11 - Beachten Sie bitte die Bedingungen der Montage auf Seite 11

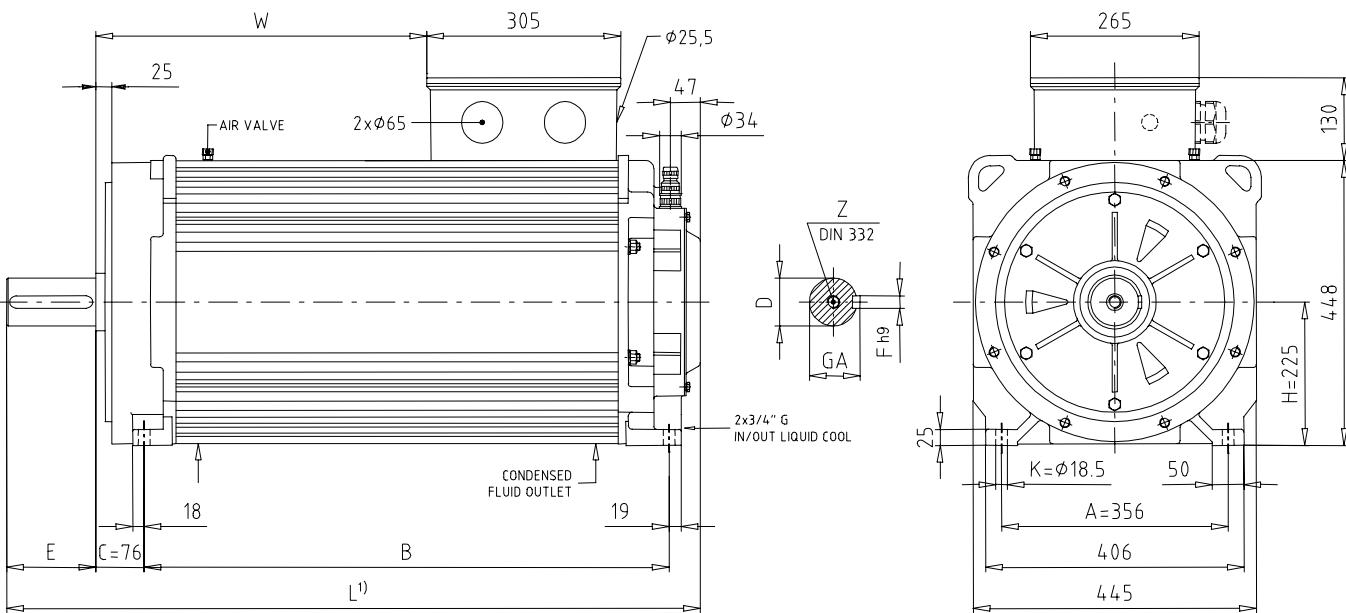
LQ 225

DIMENSIONI DI INGOMBRO - OVERALL DIMENSIONS - ABMESSUNGEN

Dimensions [mm]

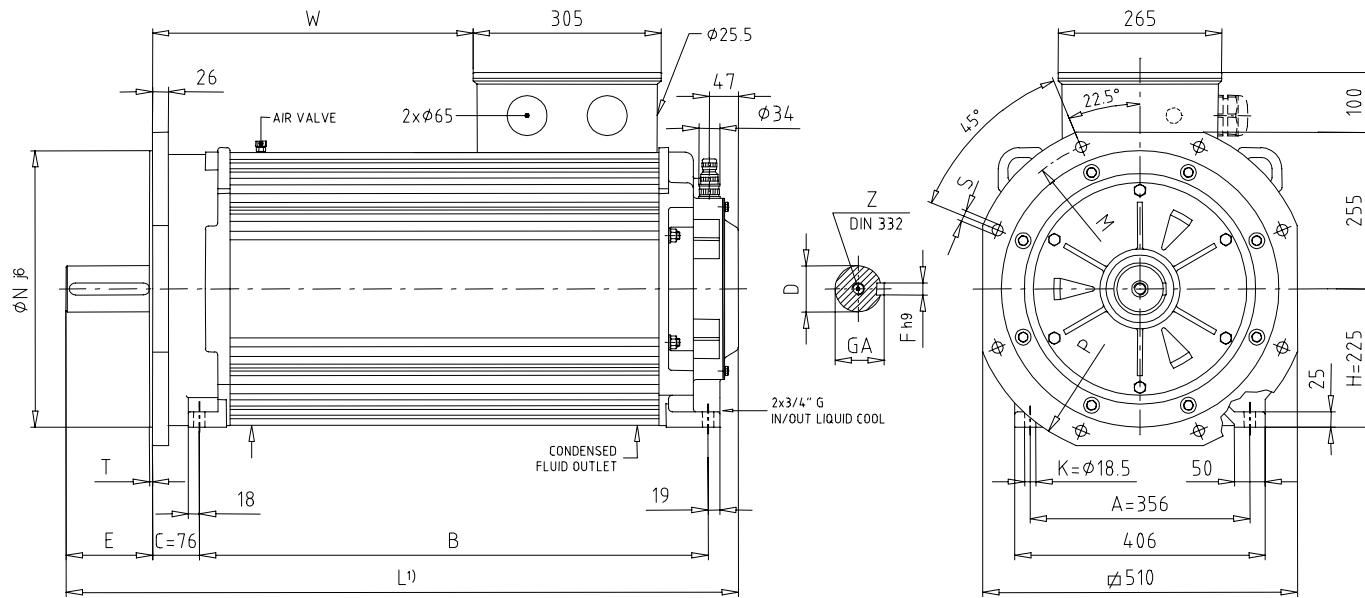
FORMA COSTRUTTIVA - CONSTRUCTION FORM - BAUFORM

B3 - IM 1001



FORMA COSTRUTTIVA - CONSTRUCTION FORM - BAUFORM

B35 - IM 2001



Size	B	D	E	F	GA	L	L1 ²⁾	M	N	P	S	T	W	Z
225 L	825	75 ^{m6}	140	20	79.5	1095	150 ^{a)}	500	450	550	18.5	5	520	
225 P	905	85 ^{m6}	170	22	90	1205	200 ^{b)}						600	M20
225 X	1025					1325							720	

Note: ¹⁾ Per motori LQ con freno aggiungere la quota L1 - For LQ motors with brake add L1 quote - Bei LQ Bremsmotoren Wert L1 hinzufügen.

a) Freno tipo Rr 360D - brake type Rr 360D - bremse typ Rr 360D

b) Freno tipo Rr 360D + encoder - brake type Rr 360D + encoder - bremse typ Rr 360D + encoder

²⁾ Opzione disponibile a richiesta - Option available on request - Verfügbares Sonderzubehör

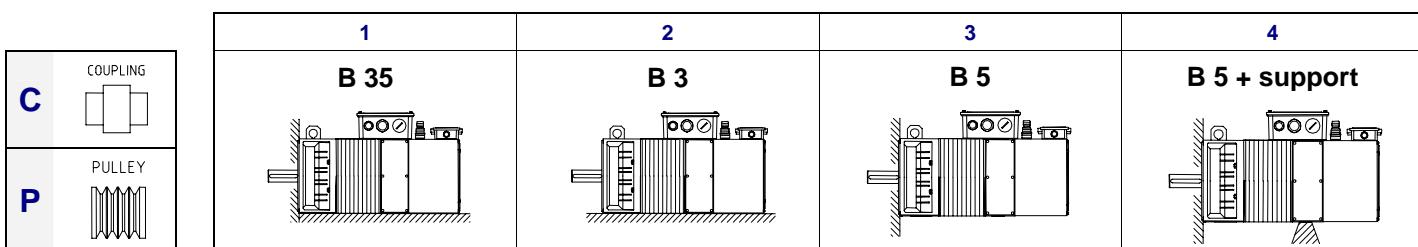
Pressacavi non forniti - Cable glands not included in the supply - Kabeltüllen gehören nicht zum Lieferumfang

Vedere condizioni di montaggio a pag. 11 - See mounting positions on page 11 - Beachten Sie bitte die Bedingungen der Montage auf Seite 11

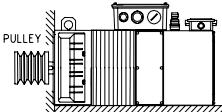
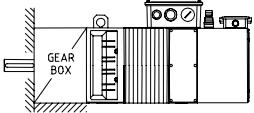
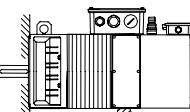
CONFIGURAZIONE MORSETTIERA	TERMINAL BOX CONFIGURATION					KLEMMEISTE-KOMFIGURATIONEN
	motor size	100	132	160	180	225
	T	S	S	S	S	S
	L	<input checked="" type="checkbox"/>				
	R	<input checked="" type="checkbox"/>				

S Versione standard – Standard version – Standardausführung
☒ Versione a richiesta – Version on request – Sonderausführung auf Anfrage

CONDIZIONI DI MONTAGGIO RACCOMANDATE	RACCOMANDED MOUNTING POSITIONS	EMPFOHLENE MONTAGEBEDINGUNGEN
--------------------------------------	--------------------------------	-------------------------------



FRAME SIZE	S	M	L	P	X
LQ 100			C or P...1, 2, 3, 4		
LQ 132			C or P...1, 2, 3, 4		C or P...1, 2, 4
LQ 160			C or P...1, 2, 3, 4		C or P...1, 2, 4
LQ 180			C or P...1, 2, 4		
LQ 225			C or P...1, 2, 4		

Puleggia Pulley Riemenscheibe		Per applicazioni con puleggia si raccomanda l'utilizzo del cuscinetto a rulli lato comando. In case of application with pulley the roller bearing is required. Bei Verwendung einer Riemenscheibe wird ein Rollenlager an der Abtriebsseite empfohlen.
Riduttore Gearbox Getriebe		Per applicazioni con riduttore ad albero innestato (senza giunto flessibile) richiedere la flangia extra precisa. In case of application with hollow shaft gearbox (without flexible coupling) ask for the extra-precise flange. Bei Anbau eines Getriebes mit Hohlwelle (ohne flexible Kupplung) wird ein hochpräziser Flansch empfohlen.
Supporto Support Lagerung		In alternativa al montaggio B35 As alternative to the B35 mounting Als Alternative zur Montageart B35

Note:
Per accoppiamenti con puleggia il carico radiale agente sull'albero motore è calcolabile secondo la formula sotto riportata.

$$F_r = 19.5 \cdot 10^6 \cdot \frac{P_n \cdot K}{D \cdot N_n} \pm P_p$$

F_r = Carico radiale in [N]
 P_n = Potenza nominale in [kW]
 N_n = Velocità nominale in [rpm]
 D = Diametro della puleggia in [mm]
 P_p = Peso della puleggia in [N]
 K = 1,25 per cinghia dentata
 2,35 per cinghia trapezoidale

Note:
For coupling with pulley, the radial load acting on the shaft is computable using the following formula:

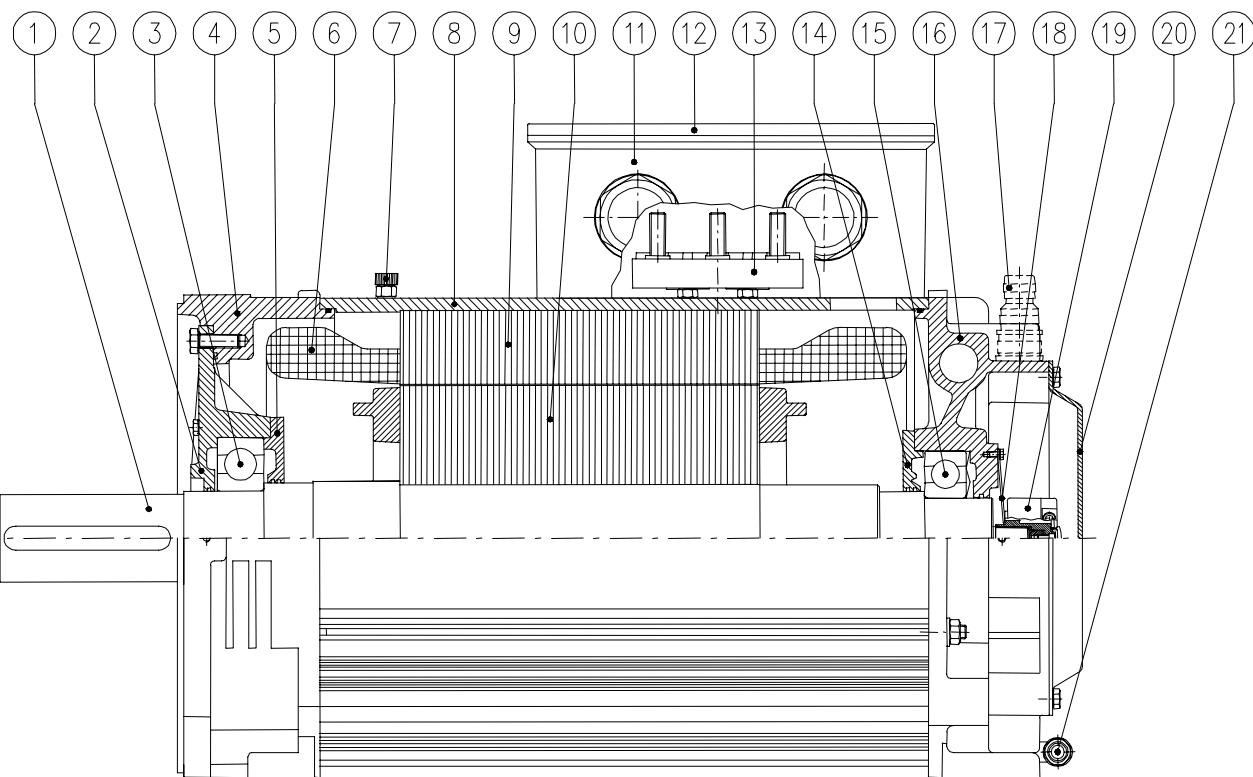
$$F_r = 19.5 \cdot 10^6 \cdot \frac{P_n \cdot K}{D \cdot N_n} \pm P_p$$

F_r = Radial load in [N]
 P_n = Nominal power in [kW]
 N_n = Nominal speed in [rpm]
 D = Diameter of pulley in [mm]
 P_p = Weight of pulley in [N]
 K = 1,25 for cog belts
 2,35 for V-belts

Hinweise:
Zum Kuppeln mit Riemenscheibe wird die auf die Motorwelle wirkende Radialbelastung nach untenstehender Formel berechnet:

$$F_r = 19.5 \cdot 10^6 \cdot \frac{P_n \cdot K}{D \cdot N_n} \pm P_p$$

F_r = Radialbelastung in [N]
 P_n = Nennleistung in [kW]
 N_n = Nenndrehzahl in [U/min] (rpm.)
 D = Riemenscheibendurchmesser in [mm]
 P_p = Riemenscheibengewicht in [N]
 K = 1,25 bei Zahnrämen
 2,35 bei Keilriemen



1	Albero	Shaft	Welle
2	Flangia supporto cuscinetto	Bearing support Flange	Fett-Schutzflansch
3	Cuscinetto lato comando	Drive-end bearing	Wälzlagar an Antriebsseite
4	Coperchio lato comando	Drive-end cover	Lagerdeckel an Antriebsseite
5	Flangia paragrasso	Grease Flange	Fett-Schutzflansch
6	Avvolgimento	Winding	Wicklung
7	Valvola aria	Air valve	Luftventil
8	Carcassa	Frame	Gehäuse
9	Statore	Stator	Stator
10	Rotore	Rotor	Rotor
11	Portamorsettiera	Terminal box	Klemmleistenaufnahme
12	Coperchio coprimorsettiera	Terminal box cover	Klemmleistendeckel
13	Morsettiera	Terminal board	Klemmleiste
14	Flangia paragrasso	Grease Flange	Kabellülle
15	Cuscinetto lato opposto comando	Non drive-end bearing	Wälzlagar an Abtriebsseite
16	Coperchio lato opposto comando	Non drive-end cover	Lagerdeckel an Abtriebsseite
17	Connettore trasduttore	Transducer connector	Meßwertgeber-Verbinder
18	Braccio reazione trasduttore	Transducer reaction arm	Reaktionsarm
19	Trasduttore	Transducer	Meßwertgeber
20	Coperchio trasduttore	Transducer cover	Meßwertgeber-Deckel
21	Ingresso / uscita liquido refrigerante	In / out cooling liquid	Kühlmittel-Ein-/Ausgang

Disegno schematico per l'identificazione dei componenti principali del motore. Le esecuzioni speciali a richiesta e le opzioni non sono contemplate. Il prodotto effettivamente fornito potrebbe differire da quanto indicato nel disegno.

Schematic drawing to identify the main components of the motor.

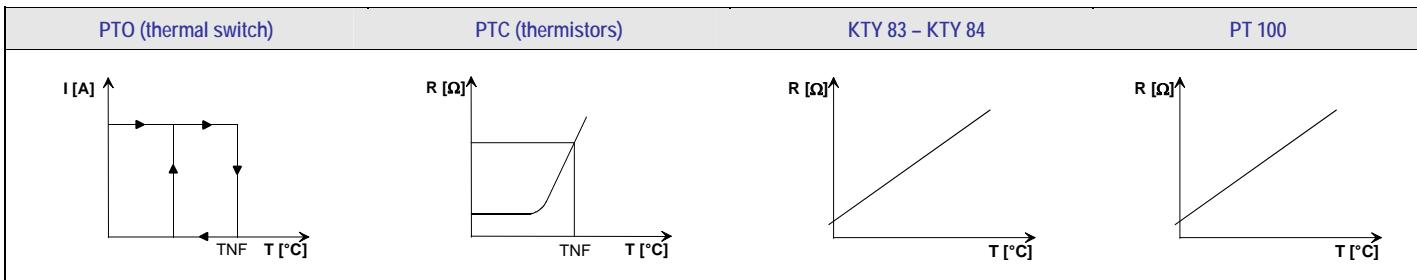
No special versions or options are shown here. The product really supply may differ from the representation in the drawing.

Schemazeichnung zur Bestimmung der Hauptbauteile des Motors. Sonderteile und Optionen sind nicht aufgeführt. Das gelieferte Erzeugnis kann von der Zeichnung abweichen.

DECLASSAMENTO	DERATING	LEISTUNGSMINDERUNG																																														
La temperatura ideale del liquido di raffreddamento è compresa tra 16°C e 20°C. Temperature del liquido superiori a 20°C determinano una diminuzione delle prestazioni del motore. Temperature del liquido inferiori a 16°C possono causare la condensazione dell'aria all'interno del motore.																																																
The ideal temperature of the coolant is between 16°C and 20°C. Any coolant temperature over 20°C determines a decrease of the motor performances. Any coolant temperature under 16°C may cause condensation of the air inside the motor.																																																
Die ideale Kühlflüssigkeitstemperatur beträgt 16°-20°C. Flüssigkeitstemperaturen über 20°C haben eine Leistungsverminderung des Motors zur Folge. Flüssigkeitstemperaturen unter 16°C können Kondensationsprobleme im Innern des Motors verursachen.		<table border="1"> <caption>Data points estimated from the graph</caption> <thead> <tr> <th>Input liquid temperature [°C]</th> <th>Motor Power / Torque [%]</th> </tr> </thead> <tbody> <tr><td>18</td><td>100</td></tr> <tr><td>20</td><td>98</td></tr> <tr><td>22</td><td>96</td></tr> <tr><td>24</td><td>93</td></tr> <tr><td>26</td><td>90</td></tr> <tr><td>28</td><td>87</td></tr> <tr><td>30</td><td>84</td></tr> <tr><td>32</td><td>81</td></tr> <tr><td>34</td><td>78</td></tr> <tr><td>36</td><td>75</td></tr> <tr><td>38</td><td>72</td></tr> <tr><td>40</td><td>69</td></tr> <tr><td>42</td><td>66</td></tr> <tr><td>44</td><td>63</td></tr> <tr><td>46</td><td>60</td></tr> <tr><td>48</td><td>57</td></tr> <tr><td>50</td><td>54</td></tr> <tr><td>52</td><td>52</td></tr> <tr><td>54</td><td>49</td></tr> <tr><td>56</td><td>46</td></tr> <tr><td>58</td><td>43</td></tr> <tr><td>60</td><td>40</td></tr> </tbody> </table>	Input liquid temperature [°C]	Motor Power / Torque [%]	18	100	20	98	22	96	24	93	26	90	28	87	30	84	32	81	34	78	36	75	38	72	40	69	42	66	44	63	46	60	48	57	50	54	52	52	54	49	56	46	58	43	60	40
Input liquid temperature [°C]	Motor Power / Torque [%]																																															
18	100																																															
20	98																																															
22	96																																															
24	93																																															
26	90																																															
28	87																																															
30	84																																															
32	81																																															
34	78																																															
36	75																																															
38	72																																															
40	69																																															
42	66																																															
44	63																																															
46	60																																															
48	57																																															
50	54																																															
52	52																																															
54	49																																															
56	46																																															
58	43																																															
60	40																																															

TRASDUTTORE (ENCODER) ²⁾	TRANSDUCER (ENCODER) ²⁾	MEBWANDLER (ENCODER) ²⁾																																	
<p>IMPULSI - PULSES</p> <p>360, 512, 1024, 2000, 2048, 4096, 5000 4....6 Vdc 5V TTL (Line driver RS 422)</p> <p>360, 512, 1024, 2000, 2048, 4096, 5000 10....30 Vdc 5V TTL (Line driver RS 422)</p> <p>360, 512, 1024, 2000, 2048, 4096, 5000 10....30 Vdc 10...30V HTL (push-pull)</p> <p>Incremental 1024, 2048 4,7....6 Vdc 1V p/p Sinus (2 sinus + marker)</p> <p>SinCos Absolute single turn 1024 ppr 7....12 Vdc Hiperface - 32768 step/rev</p> <p>SinCos Absolute multi turn 1024 ppr 7....12 Vdc Hiperface - 32768 x 4096 step/rev</p>		<p>10 PINS CONNECTOR</p> <table border="1"> <caption>Pinout for 10 PIN CONNECTOR</caption> <thead> <tr> <th>PIN</th> <th>Incremental Encoder</th> <th>Absolute Encoder</th> </tr> </thead> <tbody> <tr><td>A</td><td>(ch. A)</td><td>+ SIN</td></tr> <tr><td>B</td><td>(ch. Z)</td><td>Data +</td></tr> <tr><td>C</td><td>(ch. B)</td><td>+ COS</td></tr> <tr><td>D</td><td>--</td><td>--</td></tr> <tr><td>E</td><td>SHIELD</td><td>SHIELD</td></tr> <tr><td>F</td><td>(+....Vdc)</td><td>+....Vdc</td></tr> <tr><td>G</td><td>(GND - 0V)</td><td>0V...(GND)</td></tr> <tr><td>H</td><td>(ch. A-)</td><td>REF SIN</td></tr> <tr><td>I</td><td>(ch. Z-)</td><td>Data -</td></tr> <tr><td>J</td><td>(ch. B-)</td><td>REF COS</td></tr> </tbody> </table>	PIN	Incremental Encoder	Absolute Encoder	A	(ch. A)	+ SIN	B	(ch. Z)	Data +	C	(ch. B)	+ COS	D	--	--	E	SHIELD	SHIELD	F	(+....Vdc)	+....Vdc	G	(GND - 0V)	0V...(GND)	H	(ch. A-)	REF SIN	I	(ch. Z-)	Data -	J	(ch. B-)	REF COS
PIN	Incremental Encoder	Absolute Encoder																																	
A	(ch. A)	+ SIN																																	
B	(ch. Z)	Data +																																	
C	(ch. B)	+ COS																																	
D	--	--																																	
E	SHIELD	SHIELD																																	
F	(+....Vdc)	+....Vdc																																	
G	(GND - 0V)	0V...(GND)																																	
H	(ch. A-)	REF SIN																																	
I	(ch. Z-)	Data -																																	
J	(ch. B-)	REF COS																																	

²⁾ Opzione disponibile a richiesta – Option available on request – Verfügbares Sonderzubehör



DATI	DATA	DATEN	PTO	PTC	KTY84	KTY83	PT 100
Misura della temperatura	Temperature measure	Temperaturmessung	NO	NO	YES	YES	YES
Tipo di segnale	Type of signal	Signaltyp	NC	Non-lin.res.		Linear resistance.	
Temperatura di intervento	Intervention temp.	Temperatur bei Untersuch.	150 °C	150 °C.	-	-	-
Resistenza @ 0°C	Resistance @ 0°C	Widerstand @ 0°C	< 1 Ω	20 ÷ 750 Ω	493 Ω	820 Ω	100 Ω
Resistenza @ 40°C	Resistance @ 40°C	Widerstand @ 40°C	< 1 Ω	20 ÷ 750 Ω	668 Ω	1118 Ω	115.5 Ω
Resistenza @ 150°C	Resistance @ 150°C	Widerstand @ 150°C	< 1 Ω	≤ 1300 Ω	1340 Ω	2225 Ω	157.3 Ω
Resistenza dopo l'intervento	Res. after the intervention	Widerstand nach Untersuch.	∞	≥ 4000 Ω	-	-	-
Tensione di alimentazione	Nominal supply voltage	Nominale Versorgungsspan.	110Vac	≤ 2.5 Vdc	-	-	-
Corrente massima	Max current	Maximaler Strom	1 A	2 mA	2 mA	2 mA	2 mA
Temperatura di ripristino	Reset temperature	Rücksetztemperatur	< 95 °C	-	-	-	-

FRENI	BRAKES	BREMSEN
I freni eletromagnetici adottati per questa serie di motori sono di stazionamento, a bassa inerzia e ad azione frenante per mancanza di alimentazione.	The electromagnetic brakes adopted for this series of motors are for parking, with low inertia and fail safe type.	Die elektromagnetischen Bremsen dieser Reihe sind Festhaltebremsen mit geringem Trägheitsmoment u. Eingreifen der Bremse bei Stromabfall.
☞ Note Con l'applicazione del freno la velocità massima del motore (n_{max}) è limitata. Il funzionamento in verticale limita ulteriormente la velocità massima ed in alcuni casi non è consentito. Consultare il ns. ufficio tecnico per maggiori dettagli.	☞ Note With the application of the brake, the maximum speed of the motor (n_{max}) is limited. The installation in the vertical position limits further the maximum speed and in some cases it is not permitted. Please refer to our technical office for further details.	☞ Hinweise Bei Verwendung der Bremse bei Höchstdrehzahl des Motors (n_{max}) ist diese. Der Betrieb in vertikaler Position ist weiterhin die Höchstdrehzahl eine Begrenzung.
Il valore Q max (lavoro massimo ammissibile per ogni singola frenata) si calcola con la seguente formula. The value Qmax (max admissible work for every single breaking) can be calculated as following.	$Q \text{ max} = J_{\text{tot}} * \Delta n^2 / 182.5$ $\Delta n = \text{initial braking speed (rpm)}$	$J_{\text{tot}} = \text{motor + load inertia (kgm}^2\text{)}$
Sw ON = tempo di chiusura del freno (albero motore libero di ruotare) – sw ON = brake closing time (motor shaft free to rotate). Sw OFF = tempo di apertura del freno (albero motore frenato) – sw OFF= brake opening time (motor shaft braked).		